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Yuan, T., +, *J A I F*, 6, 2 (December 2011), 131–149.

link-analysis

Biermann, J., +, *J A I F*, 8, 2 (December 2013), 101–118.

localization

Song, X., +, *J A I F*, 8, 1 (July 2013), 3–14.

LRKF

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M

m-Best Soft Assignment Algorithm

Han, X., +, *J A I F*, 7, 1 (June 2012), 78–96.

Mahler/Fix's rule

Arnborg, S., *J A I F*, 1, 1 (July 2006), 75–90.

Maneuvering target

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maximum likelihood

Belfadel, D., +, *J A I F*, 9, 2 (December 2014), 59–74.

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maximum likelihood estimate

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maximum likelihood estimation

Crouse, D. F., +, *J A I F*, 8, 1 (July 2013), 73–89.

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maximum likelihood fusion

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Medical Decision Support Systems

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Medical Reasoning

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MHT

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military application

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MIMO radar

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minimum variance distortionless response (MVDR)

Ravindra, V. C., +, *J A I F*, 5, 2 (Dec. 2010), 88–107.

misassociation

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model-based classifier

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modelling

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moving target identification

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multi-channel signal subspace (MSS)

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multi-criteria classification

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multi-hypothesis tracking

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multi-sensor multi-target tracking

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multi-sensor target tracking

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multidimensional assignment

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Multimodal biometric score fusion

Zheng, Y., +, *J A I F*, 9, 2 (December 2014), 124–135.

multiple dimension assignment (MDA)

Zhang, S., +, *J A I F*, 9, 1 (July 2014), 38–46.

multiobjective optimization

Jilkov, V. P., +, *J A I F*, 4, 1 (July 2009), 27–39.

multiple-hypothesis tracking

Coraluppi, S., +, *J A I F*, 7, 2 (December 2012), 153–164.

Multiple-Model Adaptive Estimator

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multisensor tracking

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Blair, W. D., +, *JAIF*, **7**, 1 (June 2012), 28–45.
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multispectral face recognition

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multistatic

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multitarget multisensor

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Multitarget Multisensor Tracking

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multitarget tracking filters

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multi-sensor tracking

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Naval Anti-Air Warfare

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nearest neighbor

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Nonlinear Kalman Filtering

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non-uniform quantization

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O

OFDM modulation

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Organizational Structures Identification

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out-of-sequence measurement

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P

particle filtering

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passive acoustic sensor network

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Passive radar

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passive sensor

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PCRLB, LFM

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performance analysis

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performance evaluation

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performance model

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Performance Prediction

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PMHT

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point cloud

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point processes

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Possibilistic Reasoning

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posterior Cramer-Rao lower bound

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predetection Fusion

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Probability generating functional

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probability hypothesis density

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Probability hypothesis density filter

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profile-free method

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proportional conflict redistribution rules

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Quadratic Assignment Problem

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qualitative beliefs

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R

radar

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Real-time Fusion

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realistic sensor data

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reasoning

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recursive filtering

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reflection

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resource allocation

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resource management

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restless bandits

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risk

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road map

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rollout algorithm

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S

S²KF

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S-D algorithm

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Sampling

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Schmidt-Kalman filter

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score fusion evaluation metric

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Secular function

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Selection Bias

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self-fusion

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sensor assignment

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sensor fusion

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Sensor Layout

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sensor localization

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sensor management

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Sensor network

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Sensor Networks

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sensor resource management

- Chang, K. C., +, *JAIF*, 1, 2 (Dec. 2006), 95–107.

sensor scheduling

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Shooter localization

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Similarity Estimation

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similarity index

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situation assessment

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Situation Awareness

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situational awareness

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smoothing

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social networks

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sonar

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spline

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Stansfield estimator

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state constraints

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statistical efficiency

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stereo camera

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structure discovery

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structured hypotheses

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subgraph matching

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submodular minimization

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sudden maneuvers

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surface estimation

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surveillance

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target attributes

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Target Engageability

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Target Existence Uncertainty

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target tracking

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target-death problem

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TBM, Monte Carlo simulation

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templates

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test sequencing

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threat evaluation

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threat prediction

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track association

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track fusion

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track-before-detect

- Davey, S. J., *JAIF*, 6, 2 (December 2011), 167–186.

Track-to-Track

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Track-to-track association

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tracking

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UAV

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uncertainty

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Uncertainty Quantification

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unscented transform

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voiting algorithms

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wake

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weapon allocation

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