Regular Papers

Multisensor Track-to-Track Association for Tracks with Dependent Errors

Yaakov Bar-Shalom, University of Connecticut, USA
Huimim Chen, University of New Orleans, USA

Joint Particle Filtering of Multiple Maneuvering Targets from Possibly Unassociated Measurements

Henk Blom and Edwin Bloem, National Aerospace Laboratory NLR, The Netherlands

Fusion Algorithms for Face Localization

Rachid Belaroussi, Lionel Prevost, and Maurice Milgram
University Paris VI, France

Fusion of Redundant Information in Brake-By-Wire Systems, Using a Fuzzy Voter

Reza Hoseinnezhad and Alireza Bab-Hadiashar
Swinburne University of Technology, UK

Augmented State Integrated Probabilistic Data Association

Rajib Chakravorty and Subhash Challa, University of Technology, Australia

Robust Bayesianism: Relation to Evidence Theory

Stefan Arnborg, Royal Institute of Technology, Sweden

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